

Active Mobility (Gardens by the Bay — Exemption) Order 2022

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No. S 88

ACTIVE MOBILITY ACT 2017

ACTIVE MOBILITY (GARDENS BY THE BAY — EXEMPTION) ORDER 2022

In exercise of the powers conferred by section 66 of the Active Mobility Act 2017, the Minister for Transport makes the following Order:

Citation and period in force

1.—(1) This Order is the Active Mobility (Gardens by the Bay — Exemption) Order 2022.

(2) This Order is in force for the period between 14 February 2022 and 31 October 2022 (both dates inclusive).

Definitions

2. In this Order —

“specified motor vehicle” means an autonomous motor vehicle that —

- (a) is known as an auto-rider (model: NAVYA ARMA); and
- (b) has complied with the requirements of the test known as the Supervised Trial Readiness Assessment (Provisional Version) for Autonomous Vehicles on Public Paths that is jointly administered by the Authority and the Centre of Excellence for Testing & Research of Autonomous Vehicles — NTU (CETRAN);

“specified person” means any of the following companies incorporated under the Companies Act 1967:

- (a) Car Club Pte. Ltd. (UEN 200912077G);
- (b) ST Engineering Autonomous Solutions Pte. Ltd. (UEN 200100708K);
- (c) Willers Pte. Ltd. (UEN 201816662N);

“specified shared path” means the part of the shared path specified in item 5 of Part 11 of the First Schedule to the Active Mobility (Shared Paths) Order 2018 (G.N. No. S 260/2018), and which is more particularly delineated by the black-coloured line in the map set out in the Schedule.

Exemption for driving specified motor vehicle

3. Section 17(1) of the Act does not apply to an individual who drives a specified motor vehicle on the specified shared path under the following conditions:

- (a) the individual (called in this Order the safety operator) is authorised by a specified person to drive the vehicle;
- (b) the safety operator —
 - (i) when the vehicle is in motion — must remain in the vehicle at all times; and
 - (ii) when the vehicle is travelling in autonomous mode — must only be engaged in the following activities:
 - (A) monitoring the movement of the vehicle;
 - (B) taking manual control of the vehicle when a failure of the autonomous system of the vehicle or other emergency is detected;